SUPPORTER 3000.







The SUPPORTER technology is refined from years of operational and "hands-on" experience by our designers. The top-side control system for KYSTDESIGN ROV's is designed with focus on providing an ergonomic, intuitive and efficient working environment. Single or dual operation stations can easily be configured to individual needs. Operator task priorities can be switched and shared between stations during operation.



The SUPPORTER ROV accommodates up to 41 electrical connectors for interface of external equipment, such as tooling, survey sensors and cameras, and all electrical power supplies are ground-fault monitored. The ROV also accommodates 24 hydraulic functions, all proportionally controlled.

The ROV control system is prepared for a variety of auto functions like AutoPOS and AutoTRACK capabilities, in addition to over-the-horizon control from a Remote Operation Center (ROC) onshore.

SPECIFICATIONS, SUPPORTER 3000

General:	
Power	115 Kw / 150 Hp
Depth rating ROV	3000 msw
Dimensions (L/W/H)	2750 / 1700 /1650 mm
Weight	3600 kg
Payload	400 kg
Through Frame Lift capacity	3000 kg
Thrusters	7 x SA300
Mechanical Capacity and Inte	
Free space inside ROV for	Open area of approx. 350 L through the entire ROV,
utility equipment:	right in front of centre of gravity.
Interface for work modules:	Four docking receptacles underneath the ROV.
	Interface for Sensors and/ or modules by threaded
	inserts on all sides of the buoyancy element.
Manipulators:	Interface for Schilling T4, RigMaster and Atlas.
Hydraulic Capacity and Interf	
Valve Pack No. 1	10 x Bi-directional Valves with proportional flow
	control, each with max flow 10 l/min. Pressure on
	VP controlled by VP No.3.
Valve Pack No. 2	10 x Bi-directional Valves with proportional flow
	control, each with max flow 10 l/min. Pressure on
	VP controlled by VP No.3.
Valve Pack No. 3	4 x Bi-directional Valves with proportional flow and
	pressure control, each with max flow 90 l/min.
Manifolds	Pressure and return manifolds mounted in front of
	Tresoure and retain manifolds mounted in none of
	the ROV. 1 x Pilot operated high flow valve with
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Aux System Capacity	the ROV. 1 x Pilot operated high flow valve with
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Camera and Lights:	10.0
Camera Interface	10x Camera connections for IP video (HD-SDI & PAL
	supported).
Pan/Tilt	Connector type: Min-K-10. Electrical
Light Interface	Capacity for ten outputs, maximum total load of
Light interface	2300W. Each output secured by 6A breakers, other
	breakers on request.
	Connector type: Seacon 5506-1503
	defined to type. deacon dood 1000
Performance:	
Bollard Pull FWD/AFT	780/770 kg
Bollard Pull LATERAL	710 kg
Bollard Pull Vertical UP	730 kg
Bollard Pull Vertical DOWN	800 kg
Speed FWD	> 1,6 m/ s
Speed LATERAL	> 0,8 m/ s
Pilot Interface:	
- Two identical pilot chairs, wh	nere all necessary controls for operating the ROV, TMS
and PDU are integrated in the	e armrests
- 1 off Multiview Controller	
- Monitors	
- Clearcom communication sy	ystem, microphone and channel selectors integrated in
pilot chair	
PDU:	
Description	Two separate cabinets. One containing breakers,
	contactors, overload relays and signal trans-
	formers. The other serving as a termination and
	isolation point for all high voltage connections.
Input	3 phase 400-420-440VAC, 60 Hz (690VAC optional)
Output	- ROV HPU 165 KVA, 3000-3150-3300VAC
	- ROV Instrument 10 KVA, 3000-3150-3300VAC
	- TMS HPU 23 KVA, 3000-3150-3300VAC
	- TMS Instrument 10 KVA, 3000-3150-3300VAC
Containers (Option):	
ROV Control Container	- 20' Container manufactured in accordance with
	DNV 2.7-1 Offshore Containers
	- Dimensions: 6058 / 2438 /3000 mm (L/W/H)
	- Air conditioned
	- Option: Zone 2 certification
ROV Workshop /	- 20' Container manufactured in accordance with
PDU Container	DNV 2.7-1 Offshore Containers
	- Dimensions: 6058 / 2438 /3000 mm (L/W/H)
	- Air conditioned
	- Contain workshop, PDU and transformers.
	- Option: Zone 2 certification
TMS (Option):	
Various options available. Cor	ntact Kystdesign for further information.