







# CONSTRUCTOR


Uniquely designed for carrying and operating large tools and modules


  
POWER  
(Kw / Hp)  
**160/220**

  
DEPTH RATING  
(msw)  
**2 - 6000**

  
DIMENSION  
L x W x H (m)  
**3,22x1,7x  
1,87**

  
WEIGHT  
(kg)  
**4600**

  
PAYLOAD  
(kg)  
**400**

  
THROUGH FRAME  
LIFT CAPACITY (kg)  
**3000**



# CONSTRUCTOR

The CONSTRUCTOR technology is refined from years of operational and "hands-on" experience by our designers. The top-side control system for KYSTDESIGN ROV's is designed with focus on providing an ergonomic, intuitive and efficient working environment. Single or dual operation stations can easily be configured to individual needs. Operator task priorities can be switched and shared between stations during operation. The CONSTRUCTOR can accommodate up to 25 additional hydraulic tooling functions, up to 21 additional survey sensors and 8 camera connectors. All hydraulic functions are proportionally controlled, and all electrical power supplies are ground fault monitored. The ROV control system offers a variety of auto-functions like AutoPOS and AutoTRACK capabilities.

GENERAL	
Power	160 / 220 Kw / Hp
Depth rating ROV	3000 (up to 6000 optional) msw
Depth rating Buoyancy	3000 (2000, 4000, 6000 optional) msw
Dimensions (LxBxH)	3,22 m X 1,7 m X 1,87 m
Weight	4600 kg
Payload	400 kg
Through Frame Lift capacity	3000 kg
Thrusters	7x SA380
MECHANICAL CAPACITY AND INTERFACES	
Free space inside ROV for utility equipment:	Open area on approx. 460 L through the entire ROV, right in front of centre of gravity.
Interface for work modules:	Four docking receptacles underneath the ROV (Spacing 670x795mm). Interface for Sensors frame and/or modules by threaded inserts on all sides of the buoyancy element.
Manipulators:	Interface for Schilling T4, RigMaster and Atlas
HYDRAULIC CAPACITY AND INTERFACES	
Valve Pack No.1	10x Bi-directional Valves with proportional flow control, each with max flow 8 l/min. Pressure on VP controlled by VP No.3.
Valve Pack No.2	10x Bi-directional Valves with proportional flow control, each with max flow 8 l/min. Pressure on VP controlled by VP No.3.
Valve Pack No.3	4x Bi-directional Valves with proportional flow and pressure control, each with max flow 80 l/min.
Manifolds	Pressure and return manifolds mounted in front of the ROV. 1x Pilot operated high flow valve with max flow 160 l/min. 1x Pilot operated high flow valve with max flow 250 l/min.
TELEMETRY/SENSOR CAPACITY AND INTERFACES	
Telemetry Link	By default the control pod and telemetry system are prepared for survey operations. Up to 6 fibre optic cables are available for communication. Total capacity in a standard system is 8 composite video channels, 36 serial communication channels and expandable to include 4 HD video channels (all in a single optical fibre). Options are Ethernet, gigabit layer 1 (4 ports) with ethernet switch (4 ports), and Multibeam PECL.
Power Distribution	All power distributed to external users, such as lights, cameras and sensors can be switched on/off from the topside computer and are equipped with individual fuses. When a sensor is switched off, it's corresponding subsea connector is galvanic isolated. Total available power 20A @ 115VAC. Available supplies: 115VAC, 24VDC, 48VDC, others on request.
Tool Interface	Max power consumption available is 20A @ 115VAC. Connector type: Seacon 5506-2008
Gyro Interface	Connector type: Seacon MinM-26#20, other on request
Sensor Interface	12 connectors are prewired for user/survey equipment. In addition 9 extra connectors can be installed. <b>Survey Sensors 1 to 8</b> Connector type: Seacon Min-K-10 - wired for 24/48VDC. Built in CP interface <b>Survey Sensors 9 to 12</b> Connector type: Seacon Min-K-8 - wired for 115VAC.
CAMERA AND LIGHTS	
Camera Interface	8 composite video camera inputs. Connector type: Seacon 5506-1508 or MinL-coax Camera interfaces 1 to 7 are prepared for use with focus & zoom cameras. Camera interface 8 is a combined manipulator communication and camera connector. HD interface is optional. F/Z lines are bipolar
Pan/Tilt	Hydraulic and/or electrical (Sidus protocol).
Light Interface	Capacity for ten dimmable lights, maximum total load of 2300W. Each output secured by 5A breakers, other breakers on request. Connector type: Seacon 5506-1503
PERFORMANCE	
Bollard Pull FWD/AFT	900
Bollard Pull LATERAL	850
Bollard Pull Vertical UP	800
Bollard Pull Vertical DOWN	900
Speed FWD	> 1,7 m/s
Speed LATERAL	> 0,9 m/s
PILOT INTERFACE	
	<ul style="list-style-type: none"> <li>Two identical pilot chairs, where all necessary controls for operating the ROV, TMS and PDU are integrated in the armrests.</li> <li>1 off Multiview Controller</li> <li>2 off 46" Video monitors</li> <li>6 off 22" Monitors</li> <li>Clearcom communication system, microphone and channel selectors integrated in pilot chair.</li> </ul>
PDU	
Description	Two separate cabinets. One containing breakers, contactors, overload relays and signal transformers. The other serving as a termination and isolation point for all high voltage connections.
Input	3 phase 400-420-440VAC, 60 Hz (690VAC optional)
Output	<ul style="list-style-type: none"> <li>ROV HPU 230 KVA, 4200-4350-4500VAC</li> <li>ROV Instrument 10 KVA, 3000-3150-3300VAC</li> <li>TMS HPU 23 KVA, 3000-3150-3300VAC</li> <li>TMS Instrument 10 KVA, 3000-3150-3300VAC</li> </ul>
CONTAINERS (OPTION)	
ROV Control Container	<ul style="list-style-type: none"> <li>20' Container manufactured in accordance with DNV 2.7-1 Offshore Containers.</li> <li>Dimensions: 6058 x 2438 x 3000mm (LxWxH)</li> <li>Air conditioned</li> <li>Option: Zone 2 certification</li> </ul>
ROV Workshop / PDU Container	<ul style="list-style-type: none"> <li>20' Container manufactured in accordance with DNV 2.7-1 Offshore Containers.</li> <li>Dimensions: 6058 x 2438 x 3000mm (LxWxH)</li> <li>Air conditioned</li> <li>Contain workshop, PDU and transformers.</li> <li>Option: Zone 2 certification</li> </ul>
TMS (OPTION)	
	Various options available. Contact Kystdesign for further information.

## KYSTDESIGN AS

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